







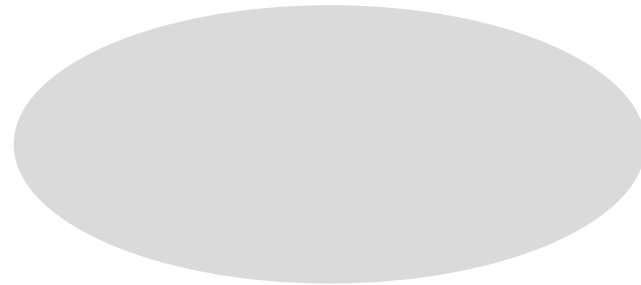
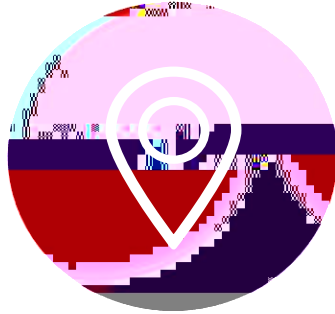
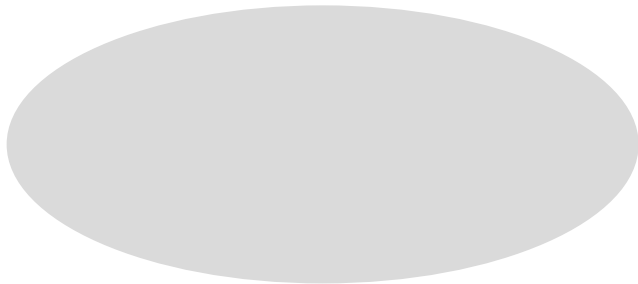
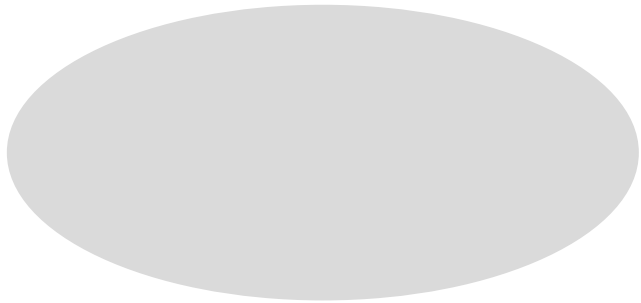
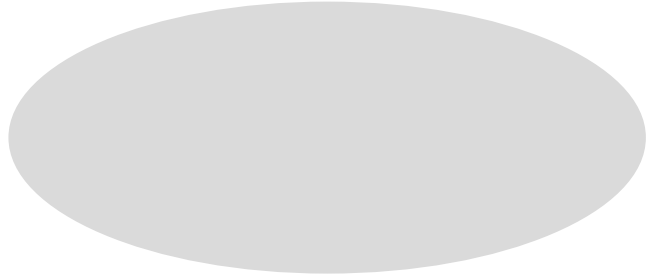


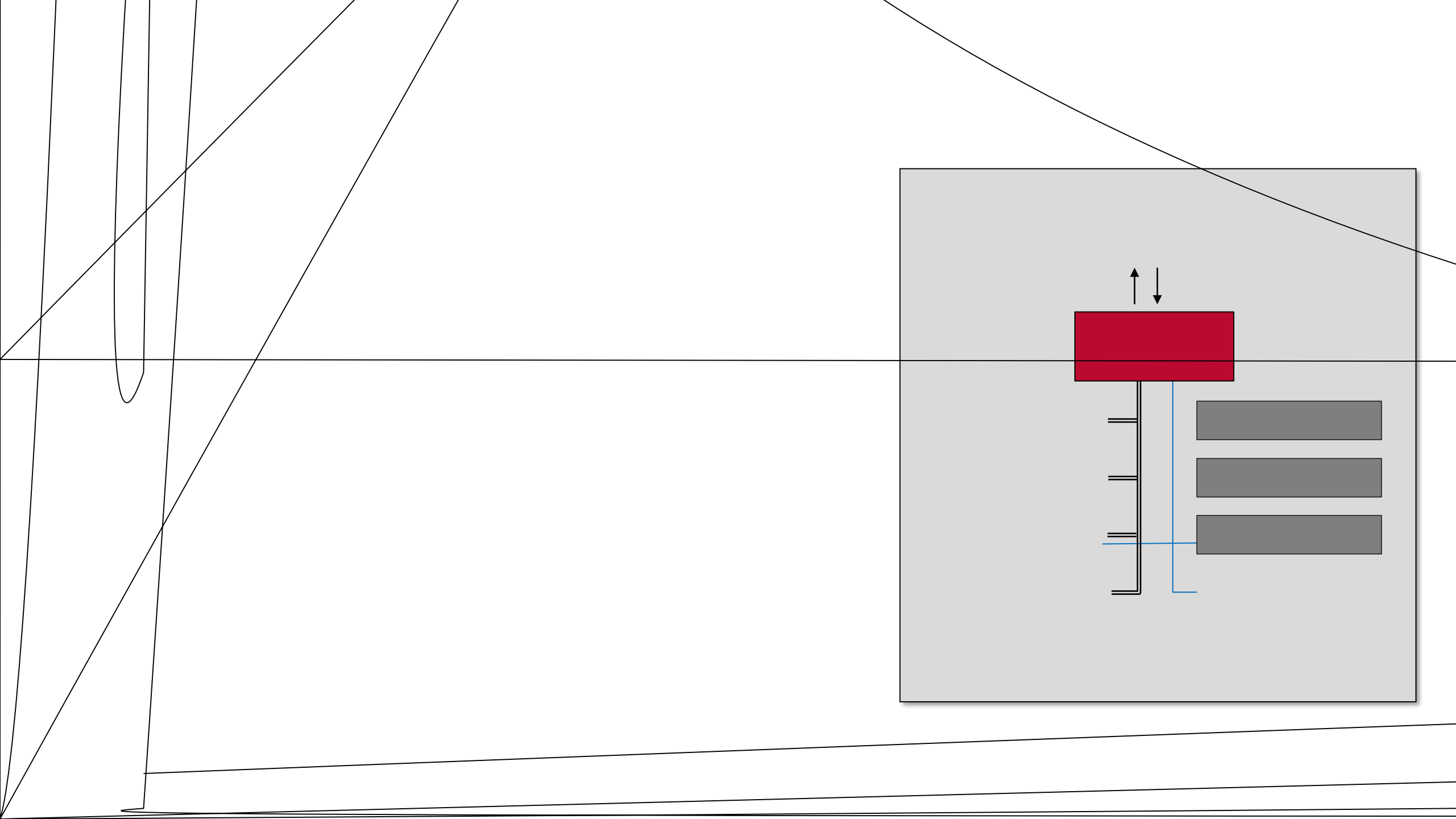
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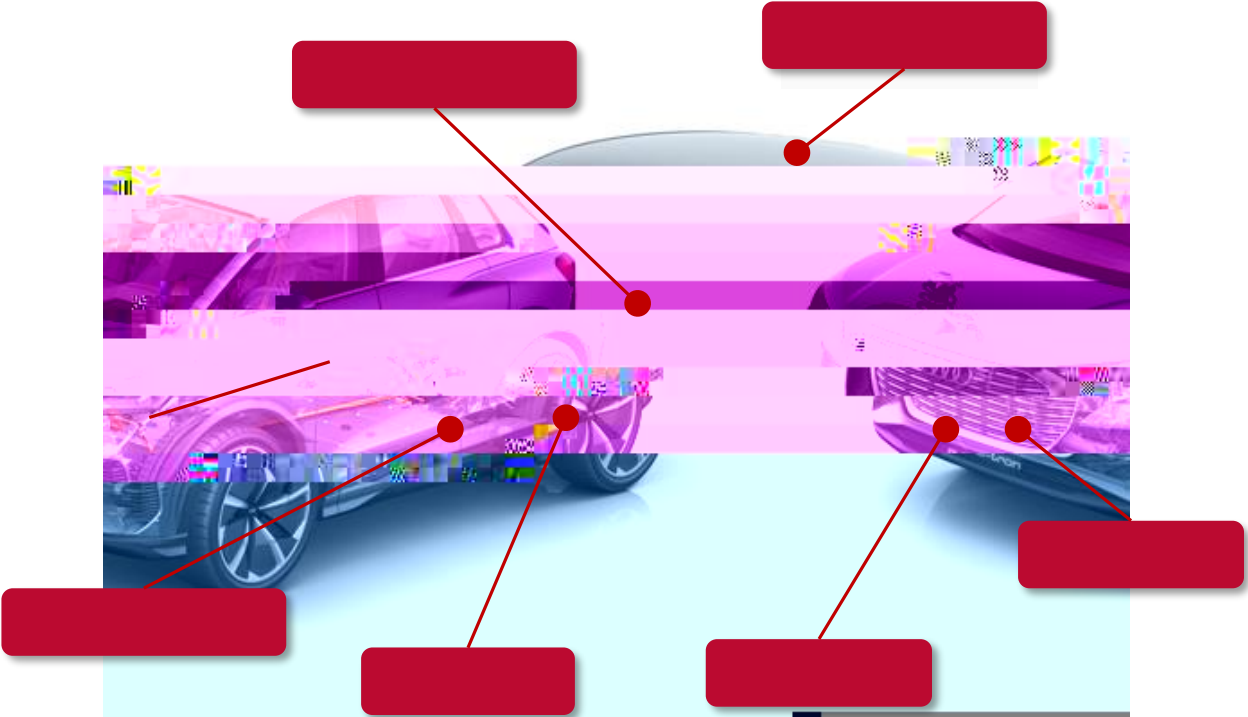
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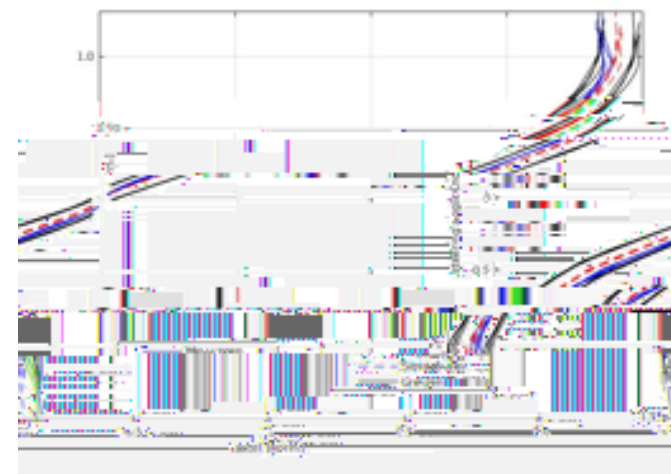
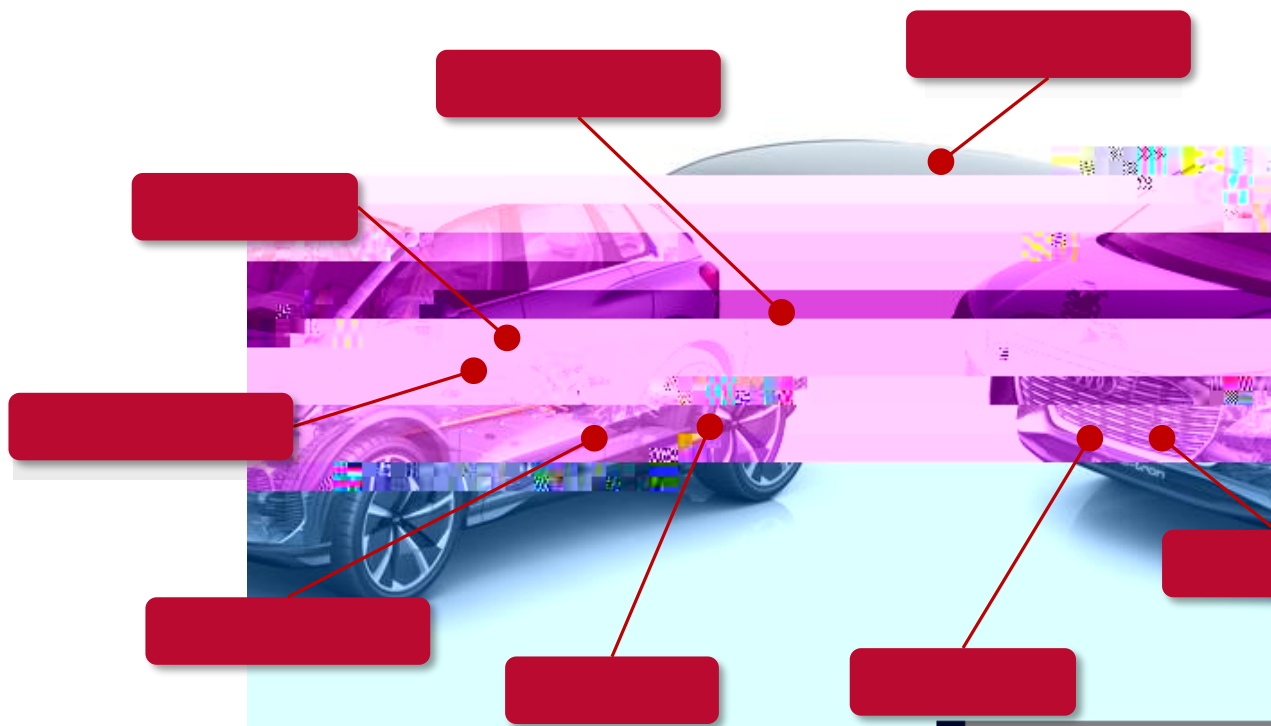
✓



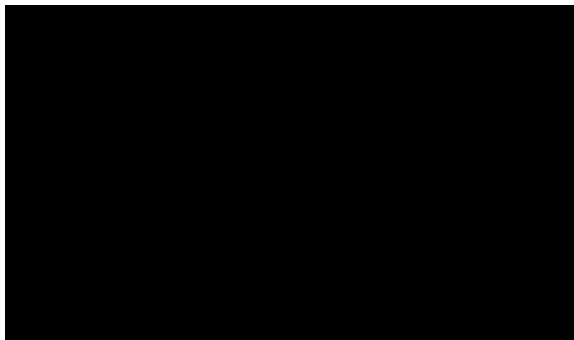
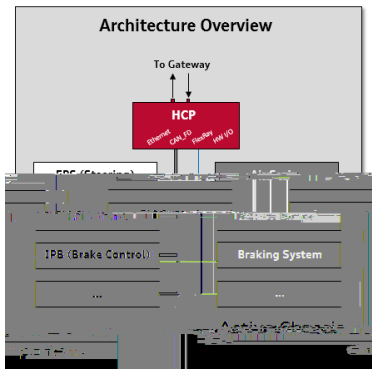












Model-Based Function Development

Matlab/Simulink

Bypass II

- > Development of functions in Targetlink
- > No need for building of a new ECU

Vehicle Model

HCP vECU

Measurement & Calibration

XCP

- > Direct access to calibration

The image shows a complex software development environment with multiple windows and toolbars. It includes a 'Bypass II' section with bullet points, a 'Vehicle Model' section, an 'HCP vECU' section, and a 'Measurement & Calibration' section. At the bottom, there is an 'XCP' section with a bullet point about direct access to calibration. The interface is dense with various icons and text, typical of a professional engineering software suite.

